Contrasted Penalized Integrative Analysis

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The High Dimensional Era of Statistics

One of the biggest buzzwords of this year: big data.

One type of big data: large $p$, small $n$.

Such data have been encountered in medicine, finance, engineering, and even social science.
Consider a generic model $Y \sim \phi(\beta^T X)$ where $\beta$ is the unknown regression coefficients. Assume a sparse or sparsified model.

With $n$ iid observations, denote $R(\beta)$ as the loss function.

Analysis goal: from a large number of candidate covariates, identify a few that are associated with the response & estimate the unknown parameters.

Penalization: a generic estimation and variable selection technique
\[ \hat{\beta} = \arg\min_\beta \{ R(\beta) + P(\beta) \} \]

\( P(\beta) \) is the model complexity measure. It often has the form \( P(\beta) = \lambda \times \sum_{j=1}^{p} f(|\beta_j|) \), that is, it is separable.

Covariates that correspond to the nonzero components of \( \hat{\beta} \) are identified as associated with the response.

When \( \log(p)/n \to 0 \) plus a few other mild conditions, \( \Pr(\text{sign}(\hat{\beta}) = \text{sign}(\beta)) \to 1 \).
**Integrative Analysis**

Important covariates identified from the analysis of high-dimensional datasets often have low reproducibility.

There are many contributing factors, among which is the small sample sizes of individual studies.

If concerned with sample size, let's have more samples (for example, NCI consortiums).

Multi-dataset approaches: meta-analysis and integrative analysis
Assume $M$ independent studies, and $n^m$ iid observations in study $m(= 1, \ldots, M)$. $\sum_m n^m << p$.

In study $m$, denote $Y^m$ as the response variable and $X^m$ as the length $p$ covariates. Assume $Y^m \sim \phi(\beta^m \, X^m)$. Denote $R^m(\beta^m)$ as the objective function, for example the negative log-likelihood function.

The overall objective function $R(\beta) = \sum_m R^m(\beta^m)$ where $\beta = (\beta^1, \ldots, \beta^M)$.

Denote $\beta^m_j$ as the $j$th component of $\beta^m$. Denote $\beta_j = (\beta^1_j, \ldots, \beta^M_j)'$, which represents the effects of covariate $j$ across $M$ datasets.
Two Candidate Models

**Homogeneity model** all datasets share the same set of susceptibility covariates. That is, $\beta^m$'s have the same sparsity structure.

**Heterogeneity model** a covariate can be associated with outcome in some datasets but not others. It includes the homogeneity model as a special case and is more flexible.
Penalized marker selection

Consider the penalized estimate

\[ \hat{\beta} = \arg \min \left\{ R(\beta) + P_{\lambda, \gamma}(\beta) \right\}. \]

Our working penalty is MCP

\[ \rho(t; \lambda_1, \gamma) = \lambda_1 \int_0^{|t|} \left( 1 - \frac{x}{\lambda_1 \gamma} \right) + dx \]

proposed by Dr. Cunhui Zhang.
Under the homogeneity model

\[ P_{\lambda, \gamma}(\beta) = \sum_{j=1}^{p} \rho \left( \| \beta_j \|_2; \sqrt{M_j \lambda_1}, \gamma \right) \]

which conducts one-dimensional selection. \( M_j \) is the "size" of \( \beta_j \). When the \( M \) datasets have matched covariate sets, \( M_j \equiv M \).

Under the heterogeneity model

\[ P_{\lambda, \gamma}(\beta) = \sum_{j=1}^{p} \rho \left( \| \beta_j \|_1; \sqrt{M_j \lambda_1}, \gamma \right) \]

which conducts two-dimensional selection. The \( \| \cdot \|_1 \) norm can be replaced with for example MCP, leading to a composite MCP penalty.
The above penalization approaches account for the grouping structure of regression coefficients.

However, there exist other structures of covariates (and regression coefficients) that have not been effectively accounted for.

Here we consider two specific examples: a within-dataset structure and an across-dataset structure.
Within-dataset structure

Here the structure describes the interplay of covariates within the same dataset.
Network based Analysis

A node corresponds to a covariate.

The most important characteristic of a network is the adjacency measure, which quantifies how closely two nodes are connected. The adjacency measure is often defined based on the notion of similarity between nodes.

Consider \( a_{jk} \), which measures the strength of connection between nodes (covariates) \( j \) and \( k \).

Assume undirected network where \( a_{jk} = a_{kj} \) for \( j, k = 1, \ldots, p \).
Construction of adjacency matrix

Denote $r_{jk}$ as the Pearson's correlation coefficient, and $\pi_{jk}$ as the canonical correlation between covariate $j$ and $k$.

(N.1) \( a_{jk} = I\{|r_{jk}| > r\} \), where $r$ is the cutoff calculated from the Fisher transformation;

(N.2) \( a_{jk} = I\{\pi_{jk} > \pi\} \), where $\pi$ is the cutoff calculated from permutation which corresponds to the null that all covariates are not associated with response;

(N.3) \( a_{jk} = \frac{1}{1+e^{-\alpha(\pi_{jk}-\pi)}} \), where $\alpha > 0$ can be determined by the scale-free topology criterion and $\pi$ is defined in N.2;
(N.4) \( a_{jk} = \pi_{jk}^\alpha \), where \( \alpha \) is defined in N.3;

(N.5) \( a_{jk} = \pi_{jk}^\alpha I\{\pi_{jk} > \pi\} \), with \( \alpha \) and \( \pi \) defined in N.3 and N.2, respectively;

(N.6) \( a_{jk} = |r_{jk}| I\{|r_{jk}| > r\} \) with \( r \) defined in N.1;

(N.7) \( a_{jk} = \pi_{jk} I\{\pi_{jk} > \pi\} \) with \( \pi \) defined in N.2.

... and many more possibilities!
Contrasted penalized estimation

$$P_{\lambda, \gamma}(\beta) = \sum_{j=1}^{p} \rho \left( \|\beta_j\|_{1(2)}; \sqrt{M_j \lambda_1}, \gamma \right)$$

$$+ \frac{1}{2} \lambda_2 d \sum_{1 \leq j < k \leq p} a_{jk} \left( \frac{\|\beta_j\|}{\sqrt{M_j}} - \frac{\|\beta_k\|}{\sqrt{M_k}} \right)^2.$$ 

Rationale: penalize the contrast between $\beta_j$ and $\beta_k$; smooth over adjacent covariates.
A more familiar formulation

Denote $\theta = (\theta_1, \ldots, \theta_p)' = \left(\frac{\|\beta_1\|}{\sqrt{M_1}}, \ldots, \frac{\|\beta_p\|}{\sqrt{M_p}}\right)'$. We express the second penalty term using a positive semidefinite matrix $L$, which satisfies

$$\theta' L \theta = \sum_{1 \leq j < k \leq p} a_{jk} (\theta_j - \theta_k)^2, \forall \theta \in \mathbb{R}^p.$$ 

Let $A = (a_{jk}, 1 \leq j, k \leq p)$ and $G = \text{diag}(g_1, \ldots, g_p)$, where $g_j = \sum_{k=1}^{p} a_{jk}$.

In a network where $a_{jk}$ is the weight of edge $(j, k)$, $g_j$ is the degree of vertex $j$. We then have $\sum_{1 \leq j < k \leq p} a_{jk} (\theta_j - \theta_k)^2 = \theta'(G - A)\theta$. Thus, $L = G - A$.

$$P_{\lambda, \gamma}(\theta) = \sum_{j=1}^{p} \rho(\theta_j; \lambda_1, \gamma) + \frac{1}{2} \lambda_2 d' L \theta.$$
Computational algorithm

With a sparse group-Lasso penalty in the analysis of a single dataset under the linear regression model, an efficient algorithm based on coordinate descent is presented in Friedman et al. (2008). Unfortunately, because of the significant differences in penalties, the algorithm is not directly applicable under the present setup.

We first consider the integrative analysis of multiple studies with continuous responses and linear regression models. Using notation similar to those in Section 2, let \( Y = X \beta + \epsilon \). Now the objective function is

\[
R(\beta) = \frac{1}{2n} \sum_{i=1}^{n} (y_i - \sum_{j=1}^{p} \beta_j x_{ij})^2 + \sum_{j=1}^{p} \lambda_j \beta_j^2.
\]

In integrative analysis, multiple studies are independent. In addition, we can carry out within-study standardization so that all coefficients are 1. Under such conditions, if \( \lambda_j > 0 \), algorithm (7) is modified to accommodate for a single group.

Reparameterize by \( \beta_j = (1/\sqrt{\lambda_j}) \hat{\beta}_j \) and consider the objective function \( R(\beta) \) with respect to the new group objective function

\[
R(\beta) = \frac{1}{2n} \sum_{i=1}^{n} (y_i - \sum_{j=1}^{p} \hat{\beta}_j x_{ij})^2 + \sum_{j=1}^{p} \lambda_j \hat{\beta}_j^2.
\]

The first-order derivatives of \( \hat{\beta}_j \)

\[
\frac{\partial R}{\partial \hat{\beta}_j} = \frac{1}{n} \sum_{i=1}^{n} (y_i - \sum_{j=1}^{p} \hat{\beta}_j x_{ij}) x_{ij} + \lambda_j \hat{\beta}_j.
\]

The solution to equation (7) is

\[
\hat{\beta}_j = \frac{1}{n} \sum_{i=1}^{n} (y_i - \sum_{j=1}^{p} \beta_j x_{ij}) x_{ij} + \lambda_j \hat{\beta}_j.
\]

When solving for \( \beta_j \), we use the following stopping criteria:

\[
\text{Stop if } |\beta_j - \hat{\beta}_j| < \epsilon.
\]

Let \( \beta_j = (1/\sqrt{\lambda_j}) \hat{\beta}_j \) and equation (7) be solved in a similar manner as with the LASSO, leading to

\[
\hat{\beta}_j = \frac{1}{n} \sum_{i=1}^{n} (y_i - \sum_{j=1}^{p} \beta_j x_{ij}) x_{ij} + \lambda_j \hat{\beta}_j.
\]

The solution to equation (7) is

\[
\hat{\beta}_j = \frac{1}{n} \sum_{i=1}^{n} (y_i - \sum_{j=1}^{p} \beta_j x_{ij}) x_{ij} + \lambda_j \hat{\beta}_j.
\]

Let \( \lambda_j = (1 - \rho_j) \lambda_j \)

\[
\hat{\beta}_j = \frac{1}{n} \sum_{i=1}^{n} (y_i - \sum_{j=1}^{p} \beta_j x_{ij}) x_{ij} + \lambda_j \hat{\beta}_j.
\]

Solving equation (7) amounts to iteratively solving equations (8) to (10) until convergence. Overall, consider the following algorithm. With tolerances measured:

1. Initialize \( s = 0 \), the estimate \( \beta^{(0)} = \beta_0 \), and the vector of residuals \( e = Y - X \beta^{(0)} \).
2. For \( j = 1, \ldots, d \),
   a. Compute \( \beta^{(s+1)}_j \): This is achieved by solving equation (7), which amounts to iterating equations (8) to (10) until convergence. In our numerical studies, convergence is achieved for all datasets within ten iterations;
   b. Update \( \beta = R(\beta^{(s+1)}) - \beta^{(s)} \);
   c. Update \( e = e - X \beta^{(s+1)} \);
3. Repeat Step 2 until convergence.
Computation is realized using an iterative coordinate descent algorithm.

With coordinate descent, we update the estimate for one group of coefficients at a time, and cycle through all groups. This process is repeated until convergence.

$R(\beta)$ and the second penalty have local quadratic forms. Their sum ($f$) is regular in the sense of Tseng (2001).

The coordinate descent solution converges to a coordinate-wise minimum point of $f$, which is also a stationary point.
Simulation

Three datasets; 100 samples per dataset; 500 covariates per subject.

500 covariates belong to 100 clusters. Covariates within the same clusters are correlated. Different clusters are independent.

Among the 500 covariates, 20 (4 clusters) have nonzero regression coefficients.

Nonzero regression coefficients $\sim Unif[0.25, 0.75]$. Random error $\sim N(0, 1)$. Log censoring time: normally distributed.
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<th>N.3</th>
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</table>

The first row is number of true positives, the second row is number of false positives, and the third row is mean prediction error.
Analysis of lung cancer prognosis studies

Lung cancer is the leading cause of death from cancer for both men and women in the US. NSCLC accounts for up to 85% of lung cancer deaths.

The UM (University of Michigan) study has 175 patients and 102 deaths. Median follow-up=53 months. The HLM (Moffitt Cancer Center) study has 79 subjects and 60 deaths. Median follow-up=39 months. The CAN/DF (Dana-Farber) study has 82 patients and 35 deaths. Median follow-up=51 months.

22,283 probe sets were profiled. We rank the probe sets using their variations and select the top 1,000 probes for downstream analysis.
Canonical correlation among all genes
Canonical correlation with probe 206561_s_at
## Numbers of identified genes and overlaps

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Evaluation of prediction performance

We generate training sets and testing sets by random splitting with sizes 2:1. Estimates are generated using the training sets only. We then make prediction for subjects in the testing sets. With the predicted linear risk scores $X\hat{\beta}$, dichotomize at the median, create two risk groups, and compute the logrank statistic, which measures the difference in survival between the two groups.

The average logrank statistics over 100 splits are 4.47 (N.1), 4.30 (N.2), 4.77 (N.3), 4.93 (N.4), 4.23 (N.5), 5.13 (N.6) and 4.03 (N.7) for SGLS and 3.77 for gMCP.
Genes identified by SGLS (N.6) but not gMCP

Gene SCGB1A1 (secretoglobin, family 1A, member 1), GPX2 (glutathione peroxidase 2), ABP1 (amiloride binding protein 1), CST1 (cystatin SN), TSPYL5 (testis-specific Y-encoded-like protein 5), ID1 (inhibitor of DNA binding 1, dominant negative helix-loop-helix protein), TUBB2A (tubulin, beta 2A class IIa), GEM (GTP binding protein overexpressed in skeletal muscle), KAL1 (Kallmann syndrome 1 sequence), PAH (phenylalanine hydroxylase), LYZ (lysozyme), PNMAL1 (paraneoplastic Ma antigen family-like), ETS2 (v-ets erythroblastosis virus E26 oncogene homolog 2) and C4BPB (complement component 4 binding protein, beta).

Searching published literature suggests that these genes may have important implications.
Across-datasets structure

Here the structure describes the relationships among regression coefficients for the same covariate across multiple datasets.
Consider a simulation scenario where the regression coefficients of response-associated covariates are the same across multiple datasets.

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<th>Benchmark D3</th>
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</table>
Under certain scenarios (for example when multiple datasets are independently generated under the same protocol), it is reasonable to expect “similar” regression coefficients across multiple datasets.

However, in practice, we never know how “close” two datasets are. We cannot rule out the scenario where a covariate has effects with conflicting signs.
Penalized estimation

\[ P_{\lambda, \gamma}(\beta) = \sum_{j=1}^{p} \rho \left( \| \beta_j \|_1(2); \sqrt{M_j} \lambda_1, \gamma \right) \]

\[ + \lambda_2 \sum_{j=1}^{d} \sum_{(k,l):k \neq l} a_{kl}^j (\beta_{kj}^l - \beta_{lj}^k)^2. \]

\[ a_{kl}^j = I\{\text{sgn}(\beta_{kj}^l) = \text{sgn}(\beta_{lj}^k)\} \]

where \( \text{sgn} \) is the sign function. \( \lambda_2 \geq 0 \) is a data-dependent tuning parameter.
When \( \text{sgn}(\beta^k_j) \neq \text{sgn}(\beta^l_j) \), covariate \( j \) demonstrates different effects in different studies. In this case, the contrast has no effect.

When \( \text{sgn}(\beta^k_j) = \text{sgn}(\beta^l_j) \), covariate \( j \) has qualitatively similar effects in studies \( k \) and \( l \). The contrast penalty shrinks the difference between \( \beta^k_j \) and \( \beta^l_j \) and encourages them to be similar.

The “smoothing” structure is mainly for covariates with nonzero effects. We may further consider

\[
a_{j}^{kl} = I(||\beta_j||_2 \neq 0) \times I\{\text{sgn}(\beta^k_j) = \text{sgn}(\beta^l_j)\}.
\]
With practical data, $\text{sgn}(\beta^k_j)$ needs to be estimated. There are several proposals (a) marginal estimation (in the spirit of screening), (b) single-dataset penalization, (c) integrative penalization, etc.

Their asymptotic consistency can be established.

Our limited experience suggests that (b) and (c) work reasonably well.

Computation is also based on coordinate descent, in a similar manner as with the previous estimate.
Simulation study

Three datasets are simulated, each with 100 subjects. For each subject, $d = 1,000$ covariates are simulated to have a multivariate normal distribution.

Under the heterogeneity model, all three datasets share five common markers. In addition, each dataset has five dataset-specific markers. Thus, across the three datasets, there are a total of 30 markers.

In addition, as a special case of the heterogeneity model, we also consider the homogeneity model.
The regression coefficients of the response-associated covariates are

(0.4, 0.5, 0.6, 0.7, 0.8, -0.4, -0.5, -0.6, -0.7, -0.8),

(0.4, -0.5, 0.6, -0.7, 0.8, -0.4, 0.5, -0.6, 0.7, -0.8),

(0.4, 0.5, 0.6, 0.7, 0.8, -0.4, -0.5, -0.6, -0.7, -0.8)

for dataset 1-3, respectively.
## Heterogeneity model

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True positive; False positive; Prediction SSE.
## Homogeneity model

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A generic framework

\[ \hat{\beta} = \arg\min \{ R(\beta) + P(\beta) + P_c(C\beta) \} \]

The matrix \( C \) specifies the contrasts. It describes the network structure among all covariates (in the same or different datasets).

Consider \( \beta^o \), a \( p \times M \) matrix. Its components that correspond to the zero components of \( \beta \) have been set as zero. That is, selection has been pre-conducted by an "oracle". Consider

\[ \hat{\beta}^o = \arg\min \{ R(\beta) + P_c(C\beta) \} \]

Assume \( C \) is known.
Some Assumptions

$M$ is fixed. $\log(p)/\sum_m n^m \to 0$.

The size of set $\{j : ||\beta_j||_2 > 0\}$ is finite.

All $X^m$s satisfy the SRC (sparse Rietz condition): all submatrices with sizes smaller than a fixed value have bounded eigenvalues.

Model specific assumptions: for example if $Y^m = \alpha^m + \beta^m X^m + \epsilon^m$, then $\epsilon^m$ has a sub-Gaussian distribution.

Main result: $Pr(\hat{\beta} = \beta^o) \to 1$
The unsolved, real problem

The contrast penalty $C$ can be data-dependent.

Consider for example network-based analysis. $C$ is closely related to the variance-covariance matrix. If no additional assumption is made and $p \gg n$, we may not have consistent estimates (of, for example, eigenvalues and eigenvectors).

We can fix the above inconsistency problem by imposing, for example, the banded structure. However, we do not know what $\hat{\beta}$ will be like with estimated $C$. 
Remarks

In high-dimensional data analysis, contrasted penalization provides an effective way to accommodate secondary data structures.

When the contrast is properly specified, simulation shows that contrasted penalization can improve selection and estimation. However, it is non-trivial to specify $C$.

Need development in these aspects: conceptual, theoretical, and computational.
Acknowledgements

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