

# Biased Quantiles

Graham Cormode

cormode@bell-labs.com

S. Muthukrishnan

muthu@cs.rutgers.edu

Flip Korn

flip@research.att.com

Divesh Srivastava

divesh@research.att.com

# Quantiles

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**Quantiles** summarize data distribution concisely.

Given  $N$  items, the  $\phi$ -quantile is the item with *rank*  $\phi N$  in the sorted order.

Eg. The **median** is the 0.5-quantile, the **minimum** is the 0-quantile.

**Equidepth histograms** put bucket boundaries on regular quantile values, eg 0.1, 0.2...0.9

Quantiles are a robust and rich summary:  
median is less affected by outliers than mean

# Quantiles over Data Streams

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**Data stream** consists of  $N$  items in arbitrary order.

Models many data sources eg network traffic, each packet is one item.

Requires linear space to compute quantiles exactly in one pass,  $\Omega(N^{1/p})$  in  $p$  passes.

$\epsilon$ -approximate computation in **sub-linear space**

- $\Phi$ -quantile: item with rank between  $(\Phi-\epsilon)N$  and  $(\Phi+\epsilon)N$
- [GK01]: insertions only, space  $O(1/\epsilon \log(\epsilon N))$
- [CM04]: insertions & deletions, space  $O(1/\epsilon \log U \log 1/\delta)$

# Why Biased Quantiles?

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IP network traffic is very **skewed**

- Long tails of great interest
- Eg: 0.9, 0.95, 0.99-quantiles of TCP round trip times

Issue: uniform error guarantees

- $\epsilon = 0.05$ : okay for median, but not 0.99-quantile
- $\epsilon = 0.001$ : okay for both, but needs too much space

Goal: support **relative** error guarantees in small space

- **Low-biased quantiles**:  $\phi$ -quantiles in ranks  $\phi(1 \pm \epsilon)N$
- **High-biased quantiles**:  $(1 - \phi)$ -quantiles in ranks  $(1 - (1 \pm \epsilon)\phi)N$

# Prior Work

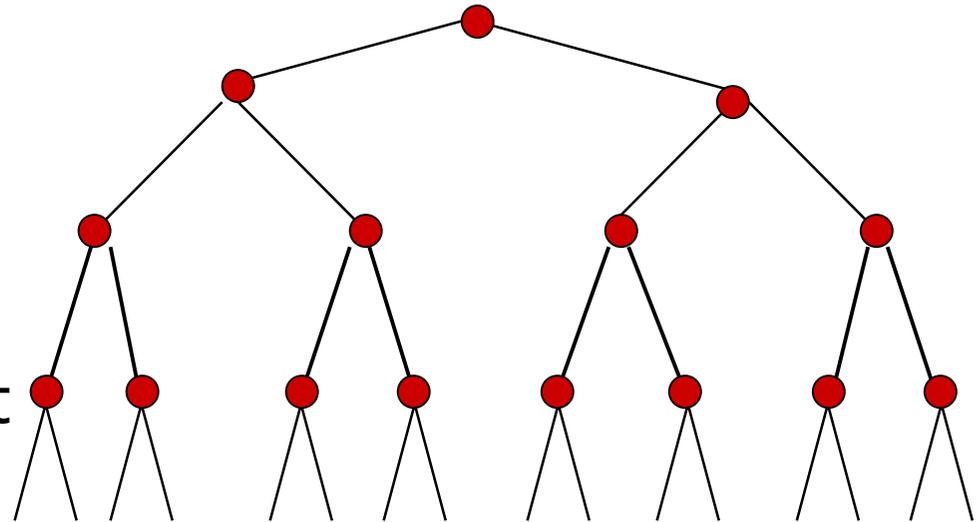
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- Sampling approach due to Gupta & Zane [GZ03]
  - Keep  $O(1/\varepsilon \log N)$  samplers at different sample rates, each keeping a sample of  $O(1/\varepsilon^2)$  items
  - Total space:  $O(1/\varepsilon^3)$ , probabilistic algorithm
- Deterministic alg [CKMS05]
  - Worst case input causes linear space usage
  - Showed lower bound of  $\Omega(1/\varepsilon \log \varepsilon N)$
- Improved probabilistic alg of Zhang+ [ZLXKW05]
  - Needs  $O(1/\varepsilon^2 \text{polylog } N)$  space and time

# Our Approach

Domain-oriented approach: items drawn from  $[1 \dots U]$ , want space to depend on  $O(\log U)$

- Impose binary tree structure over domain
- Maintain counts  $c_w$  on (subset of) nodes
- Count represents input items from that subtree



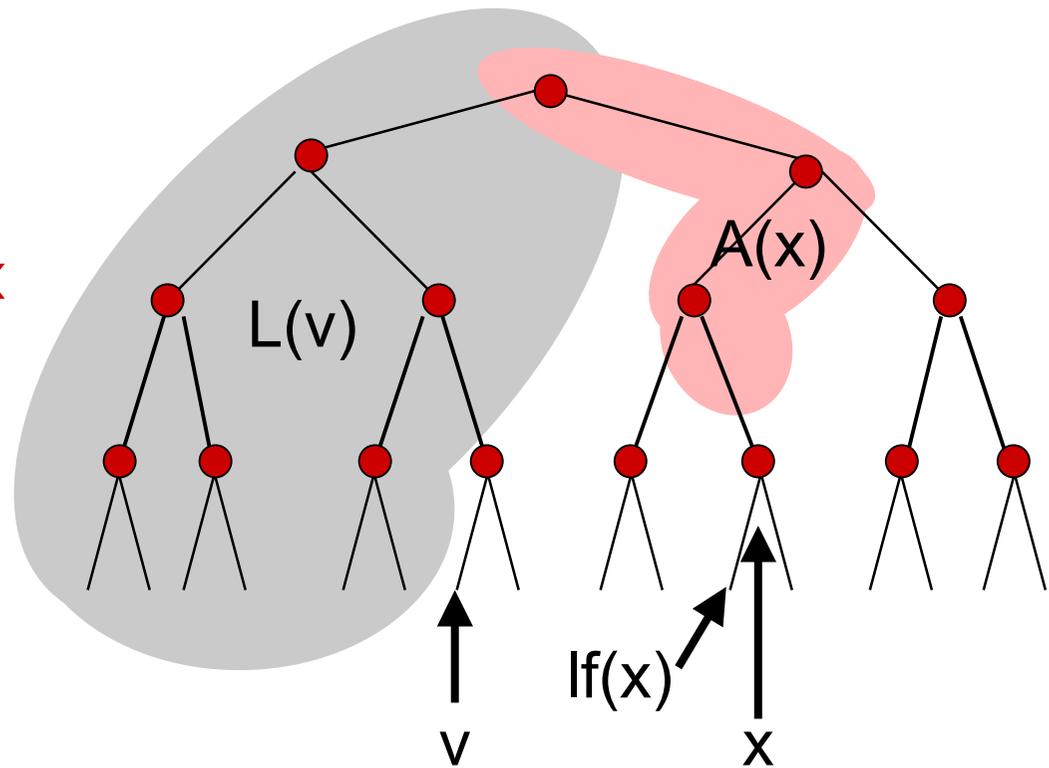
So counts to left of a leaf are from items strictly less; uncertainty in rank of item is from ancestors

Similar to [SBAS04] approach for uniform quantiles

# Functions over the tree

We define some functions to measure counts over the tree.

- $lf(x)$  = leftmost leaf in subtree  $x$
- $anc(x)$  = set of ancestors of node  $x$
- $L(v) = \sum_{lf(w) < lf(v)} C_w$   
(Left count)
- $A(x) = \sum_{w \in anc(x)} C_w$   
(Ancestor count)



# Accuracy Invariants

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To ensure accurate answers, we maintain two invariants over the set of counts:

$$\forall x. L(x) - A(x) \leq \text{rank}(x) \leq L(x) \quad \textcircled{1}$$

ensures we can deterministically bound ranks

$$\forall v. v \neq \text{lf}(v) \Rightarrow (c_v \leq \alpha L(v)) \quad \textcircled{2}$$

ensures range of possible ranks is bounded

To guarantee  $\varepsilon$ -accurate ranks, will set  $\alpha = \varepsilon / \log U$   
(since we use  $\textcircled{2}$  summed over  $\log U$  ancestors)

**Claim:** any summary satisfying  $\textcircled{1}$  and  $\textcircled{2}$  allows us to find  $r'(x)$  so  $|r'(x) - \text{rank}(x)| \leq \varepsilon \text{rank}(x)$

# Maintenance

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Need to show how to maintain the accuracy invariants, while guaranteeing space is bounded and updates are fast.

- Will `Insert` each update  $x$ . `Insert` will be defined to maintain accuracy, but space may grow
- Periodically will run a linear scan of data structure to `Compress` it.
- Will argue that these two together maintain space and time bounds.

# Data Structure

Store subset of nodes and counts as “bq-summary”

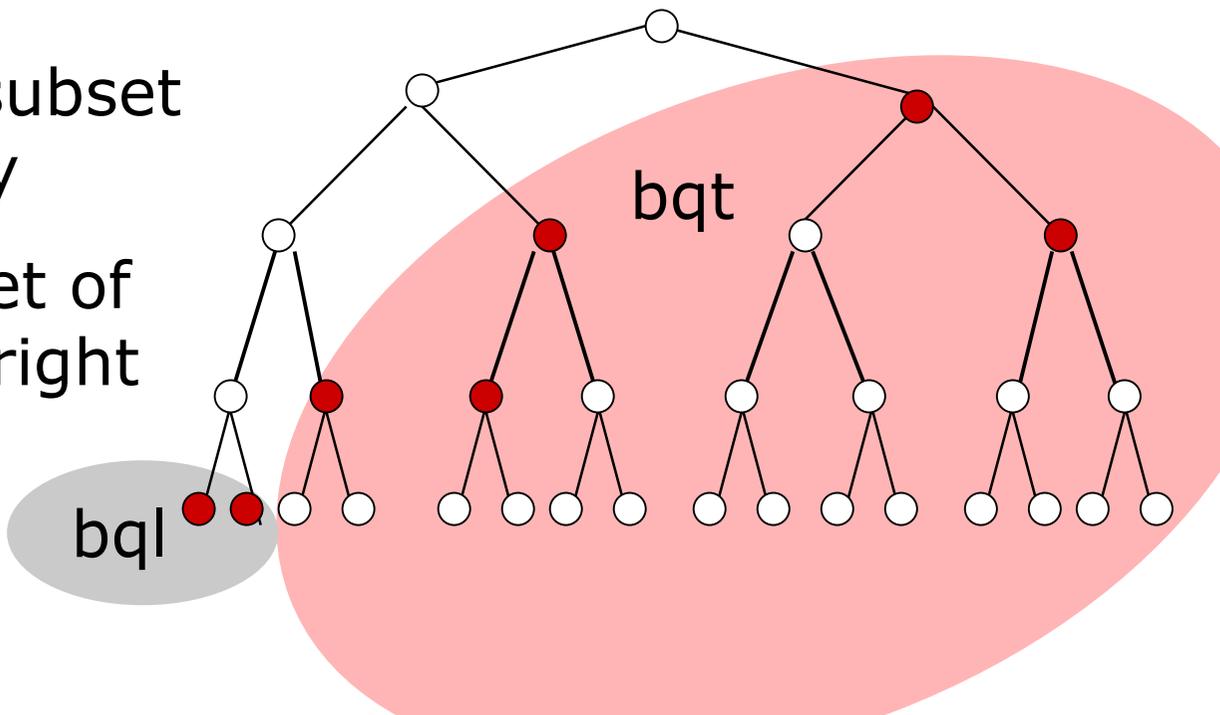
Nodes with count 0 do not need to be stored

Split bq into two: **bq-leaves (bql)** and **bq-tree (bqt)**.

This division is needed to get tightest space bounds.

- bq-leaves is a subset of leaf nodes only

- bq-tree is subset of nodes strictly to right of bq-leaves



# Space Conditions

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We will maintain four additional conditions to ensure space is bounded. Set  $z = \max_{u \in \text{bql}} u$ .

$z < \text{lf}(\text{par}(v \in \text{bqt})) \Rightarrow c_{\text{par}(v)} \geq \alpha L(\text{par}(v))$  ③  
Ensures parents of the bqt nodes are full

$1/\alpha \log(\alpha N) \geq |\text{bql}| \geq \min(N, 1/\alpha)$  ④  
Ensures not too many or too few bql nodes

$z < \min_{v \in \text{bqt}} \text{lf}(v)$  ⑤  
Ensures bq-leaves to left of bq-tree nodes

$\sum_{v \in \text{bql} \cup \text{bqt}} c_v = N$  ⑥  
Sanity check on conservation of counts

# Space Bound Outline

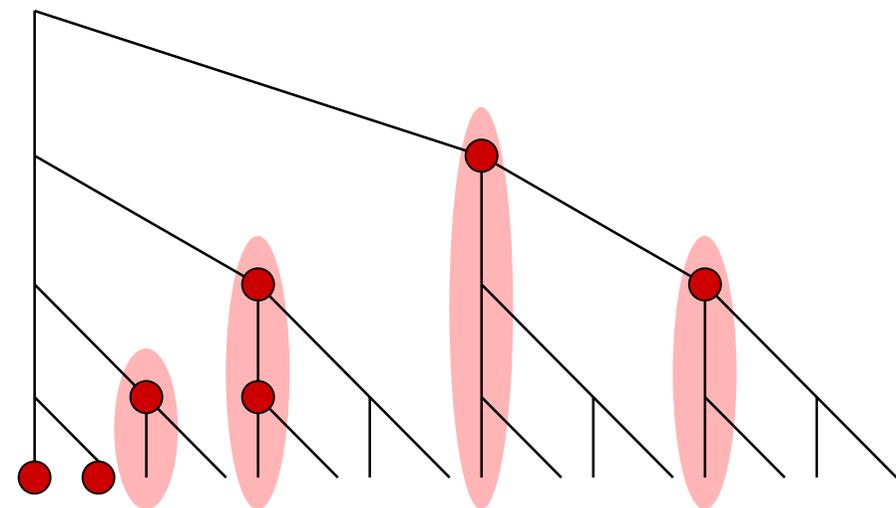
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Will show that maintaining all six conditions ensures that space is tightly bounded

Main effort is in proving size of **bqt** is bounded

Will divide **bqt** into “equivalence classes” based on increasing **L()** values

Since each **L()** value of class must increase by a multiplicative factor, can bound total space



Equivalence classes

# Equivalence Classes

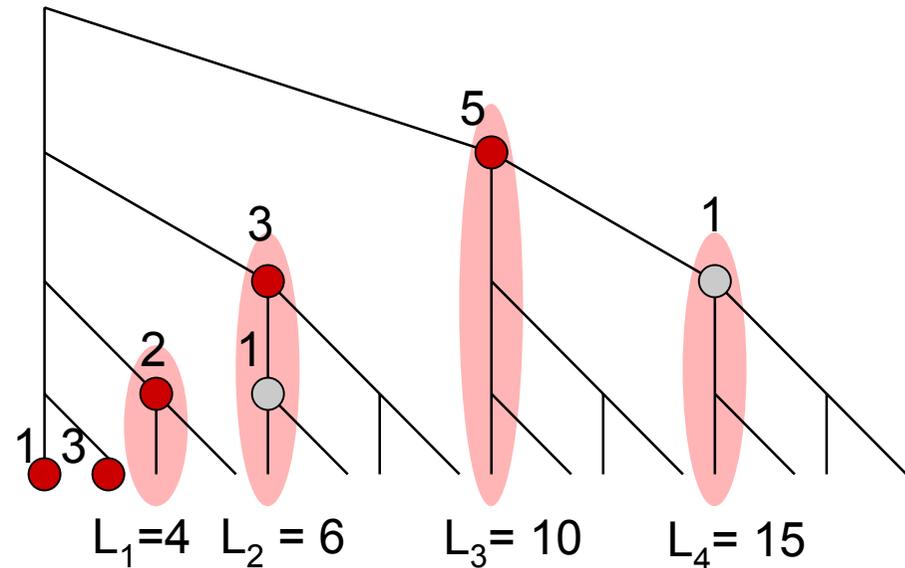
Only consider “full” nodes  $V$  in  $bqt$  (with at least one child present): by ③, for  $v \in V$ ,  $c_v = \alpha L(v)$

- Partition  $V$  into equivalence classes based on  $L(v)$

- $E_i$  is set of nodes in  $i$ 'th equivalence class, with  $L$  value =  $L_i$

- $L_1$  is sum of bq-leaves:

$$L_1 = \sum_{v \in bq} c_v$$



Example with  $\alpha = 1/2$

# Space Bound

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- By ④ we have  $|bq| = L_1 \geq 1/\alpha$
- The  $L_i$ 's increase exponentially, can show  $L_{i+1} \geq L_1 \prod_{j=1}^i (1 + \alpha |E_j|)$
- Consider item  $U+1$ , so  $\text{rank}(U+1) = N$ .
- By ⑥,  $N = L(U+1) \geq 1/\alpha \prod_{j=1}^q (1 + \alpha |E_j|)$
- Taking logs allows us to bound size of  $|bqt|$
- So total space  $= |bq| + |bqt|$   
 $= O(1/\varepsilon \log(\varepsilon N) \log U)$

# Insert Procedure

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Must show we can maintain data structure quickly

Insert allows space constraints to lapse slightly by using old (pre-calculated and stored)  $L()$  values.

Given update item  $x$ :

- Compare to  $z = \max_{u \in \text{bql}} u$
- If  $x \leq z$ , place  $x$  in  $\text{bql}$  in time  $O(1)$
- If  $x > z$  place  $x$  in  $\text{bqt}$  in time  $O(\log \log U)$ :
  - Find closest materialized ancestor  $y$  of  $x$  in  $\text{bqt}$
  - Add 1 to  $c_y$  unless this would make  $c_y > \alpha L(y)$ , if so then create child of  $y$  with count = 1

# Accuracy of Insert

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`Insert` procedure maintains ❶, ❷, ❺, and ❻

Fairly easy to check each of these, e.g.

$$\forall x. L(x) - A(x) \leq \text{rank}(x) \leq L(x) \quad \text{❶}$$

- Inserting into `bq`, increases  $L(x)$  and  $\text{rank}(x)$  for everything to the right of inserted item.
- Other conditions preserved either by inspection, or by design of `Insert` routine (eg inserting into child node if inserting into `y` would break ❷)

# Compress

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- If we keep *Inserting*, space can grow without limit, but in worst case, we add one new node per insert, so *Compress* when space doubles
- Need to periodically recompute  $L()$  values for nodes, and merge together nodes when possible
  - First, resize bq-leaves so  $|bq| = \min(N, 1/\alpha)$
  - Recompute  $z = \max_{v \in bq} v$  in time linear in  $|bq|$ , *Insert* leaves removed from  $|bq|$  into *bqt*.
  - Tricky part is compressing bq-tree...

# Compress Tree

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- “Compress Tree” operation takes a (sub)tree in  $bqt$ , ensures that each node becomes “full” (has count =  $\alpha L(v)$ ) by “pulling up” weight from below
  - For node  $v$  compute  $L(v)$  and  $wt(v) = \sum_{w \in anc(w)} c_w$
  - Set  $c_v$  as big as possible by borrowing from  $wt(v)$
  - If  $c_v = \alpha L(v)$ , then recurse on children in order
  - Else, we have accounted for all weight below, so delete all descendants
- With care,  $Compress\ Tree$  takes time  $O(|bqt|)$  and computes  $L(v)$  incrementally as a side effect
- Can show that  $Compress$  maintains conditions ①, ②, ⑤, and ⑥ and restores conditions ③ and ④

# Final Result

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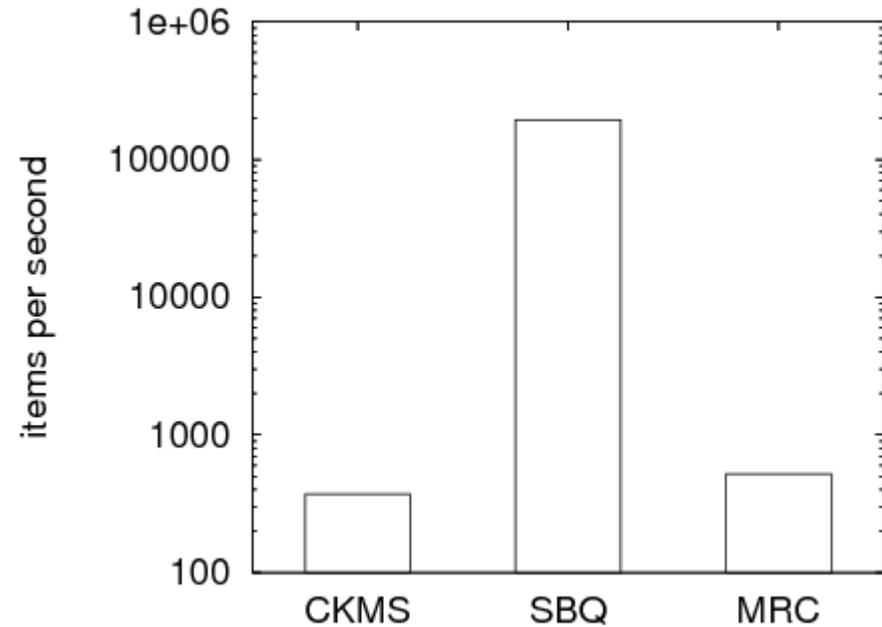
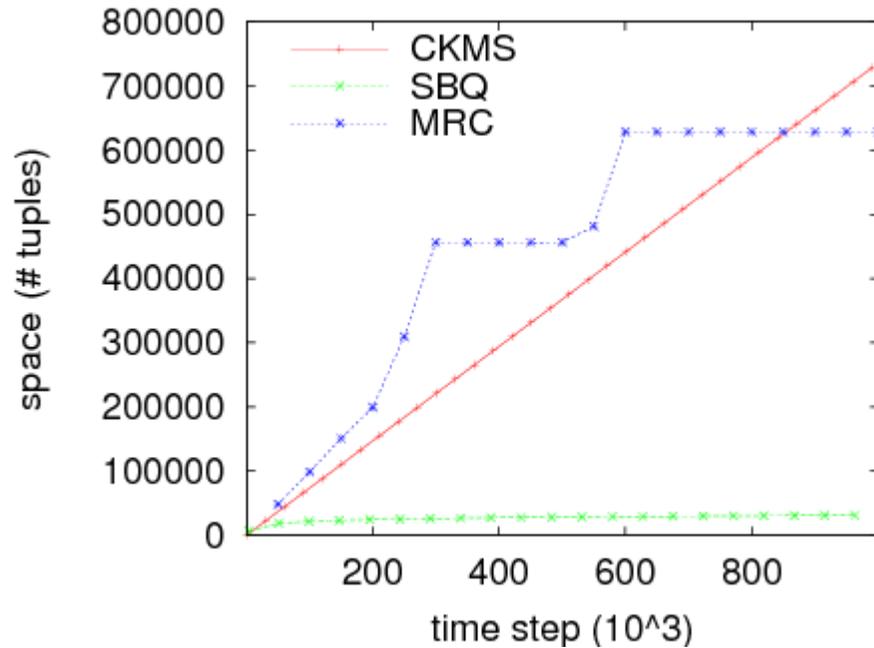
- Can answer rank queries with error  $\varepsilon \text{rank}(x)$ , using space  $O(1/\varepsilon \log \varepsilon N \log U)$ , and amortized update time  $O(\log \log U)$ .
  - Lower bound on space =  $O(1/\varepsilon \log (\varepsilon N))$
- To answer queries, need latest values of  $L(v)$ , so need time  $O(1/\varepsilon \log \varepsilon N \log U)$  to preprocess
  - Can then answer queries in time  $O(\log U)$  each
  - Alternatively, spend  $O(\log U)$  time on updates and allow  $L(v)$  values to be computed in time  $O(\log U)$
  - Quantile queries can be answered by binary searching for item with desired rank

# Extensions

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- Partially biased algorithm
  - Sometimes only need accuracy down to some  $\epsilon'N$
  - Can reduce space slightly for this weaker guarantee
  - Space required is  $O(1/\epsilon \log (\epsilon/\epsilon') \log U)$
- Uniform algorithm
  - The `Compress Tree` idea can be applied to  $\epsilon N$  error
  - bq-leaves not needed, space used is  $O(1/\epsilon \log U)$
  - Time is  $O(\log \log U)$  amortized as before

# Experimental Results



- CKMS, MRC = prior work, SBQ = this work
- Outperforms prior work in both time and space

# Commentary

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- Took some amount of effort to get the invariants and conditions “just right”:
  - Small changes to conditions meant either space or time bounds would break
  - bq-leaves needed to ensure that space bounds are as tight as possible
- Easy to merge together summaries to get summary of union (for distributed computations)
  - Linearity of **L** and **A** means everything goes through

# Conclusions

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- Close to optimal space bounds
  - What about faster updates, less work for queries?
- Made crucial use of tree-structure over universe
  - Any way to drop  $U$  and work over arbitrary domains?