

Differentially Private Mechanisms for Data Release

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Joint work with

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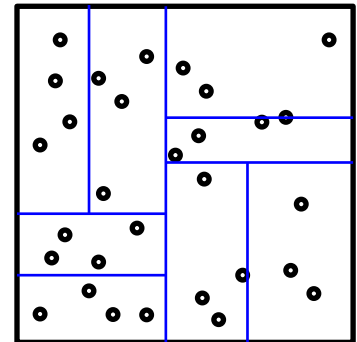
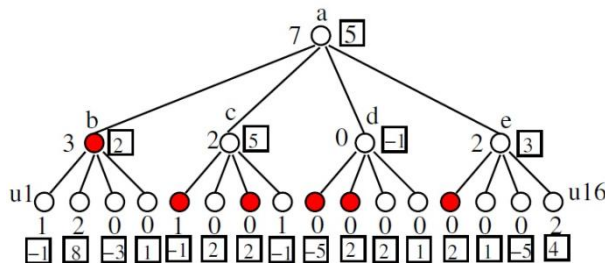
Divesh Srivastava (AT&T)

Entong Shen (NCSU)

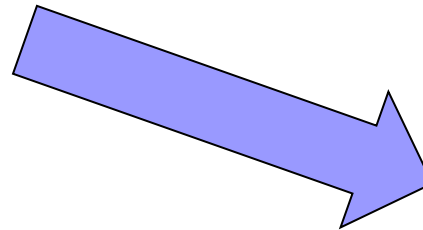
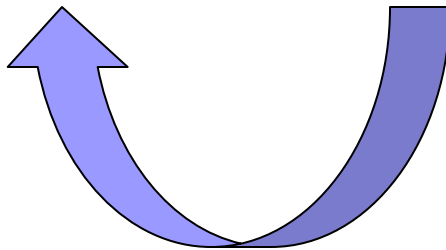
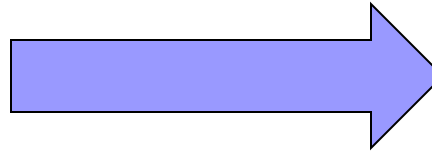
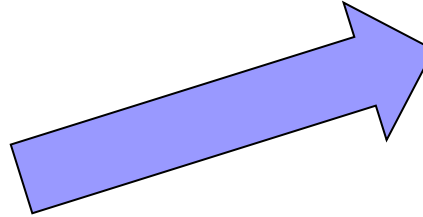
Ting Yu (NCSU)

Xiaokui Xiao (NTU)

Jun Zhang (NTU)



The anonymization scenario



Data-driven privacy

- ◆ Much interest in private data release
 - **Practical**: release of AOL, Netflix data etc.
 - **Research**: hundreds of papers
- ◆ In practice, many data-driven concerns arise:
 - Efficiency / practicality of algorithms as data scales
 - How to interpret privacy guarantees
 - Handling of common data features, e.g. sparsity
 - Ability to optimize for known query workload
 - Usability of output for general processing
- ◆ **This talk**: outline some efforts to address these issues



Differential Privacy [Dwork 06]

- ◆ **Principle**: released info reveals little about any individual
 - Even if adversary knows (almost) everything about everyone else!
- ◆ Thus, individuals should be secure about contributing their data
 - What is learnt about them is about the same either way
- ◆ Much work on providing differential privacy
 - Simple recipe for some data types e.g. numeric answers
 - Simple rules allow us to reason about composition of results
 - More complex for arbitrary data (exponential mechanism)
- ◆ Adopted and used by several organizations:
 - US Census, Common Data Project, Facebook (?)



Differential Privacy

The output distribution of a differentially private algorithm changes very little whether or not any individual's data is included in the input – so you should contribute your data

A randomized algorithm K satisfies ϵ -differential privacy if:

Given any pair of neighboring data sets,

D_1 and D_2 , and S in $\text{Range}(K)$:

$$\Pr[K(D_1) = S] \leq e^\epsilon \Pr[K(D_2) = S]$$

Achieving ϵ -Differential Privacy

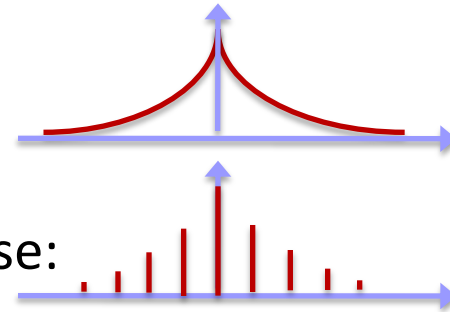
(Global) Sensitivity of publishing:

$$s = \max_{x, x'} |F(x) - F(x')|, \text{ } x, x' \text{ differ by 1 individual}$$

E.g., count individuals satisfying property P : one individual changing info affects answer by at most 1; hence $s = 1$

For every value that is output:

- Add Laplacian noise, $\text{Lap}(\epsilon/s)$:
- Or Geometric noise for discrete case:



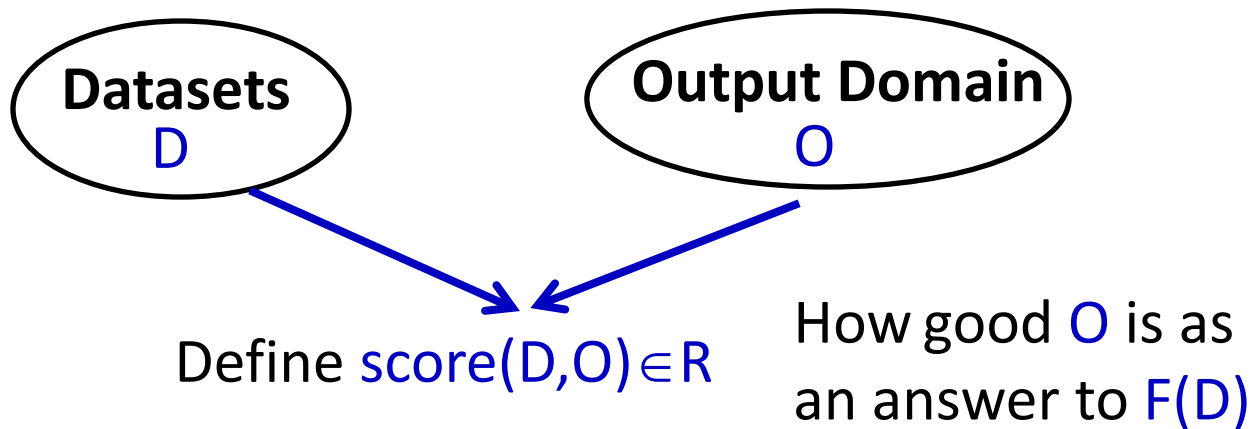
Simple rules for composition of differentially private outputs:

Given output O_1 that is ϵ_1 private and O_2 that is ϵ_2 private

- (Sequential composition) If inputs overlap, result is $\epsilon_1 + \epsilon_2$ private
- (Parallel composition) If inputs disjoint, result is $\max(\epsilon_1, \epsilon_2)$ private

Exponential Mechanism [MT07]

Given function F : Datasets $\rightarrow$ Outputs



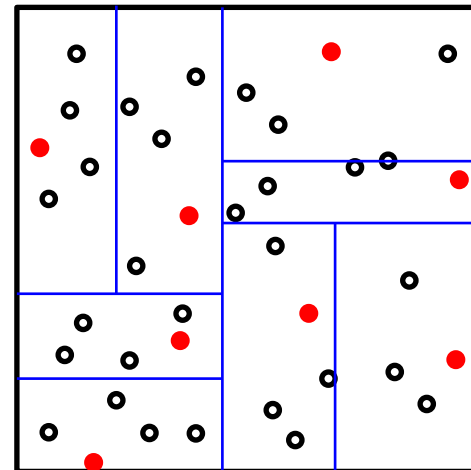
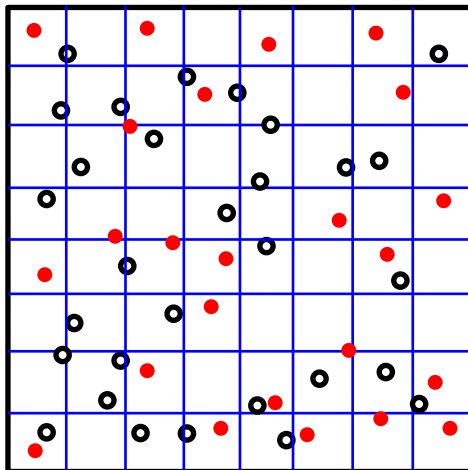
Exponential Mechanism: Return O with probability

$$\Pr[O] \propto \exp\left(\frac{\epsilon}{2\Delta} \text{score}(D, O)\right)$$

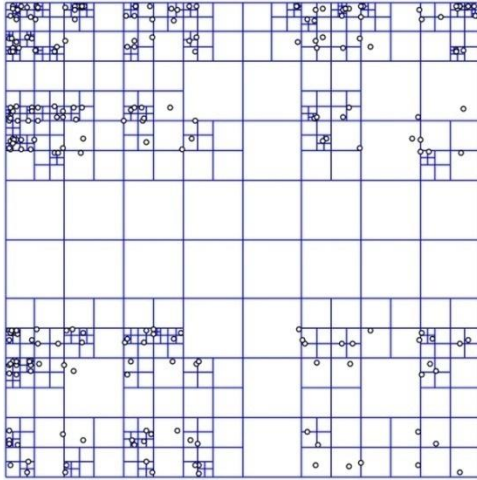
where $\Delta = \max |\text{score}(D, O) - \text{score}(D', O)|$,
taken over outputs O , neighbouring datasets D, D'

Sparse Spatial Data [ICDE 2012]

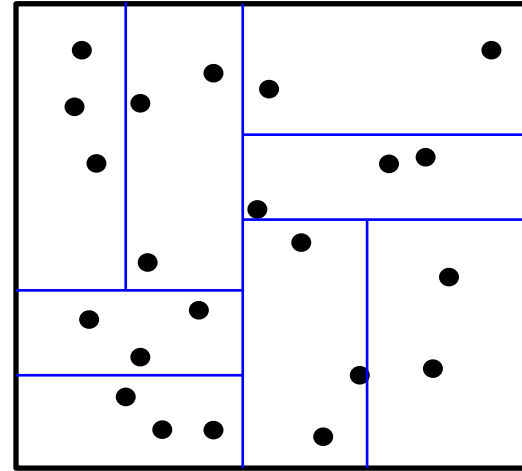
- ◆ Consider location data of many individuals
 - Some dense areas (towns and cities), some sparse (rural)
- ◆ Applying DP naively simply generates noise
 - lay down a fine grid, signal overwhelmed by noise
- ◆ **Instead:** compact regions with sufficient number of points



Private Spatial decompositions



quadtree



kd-tree

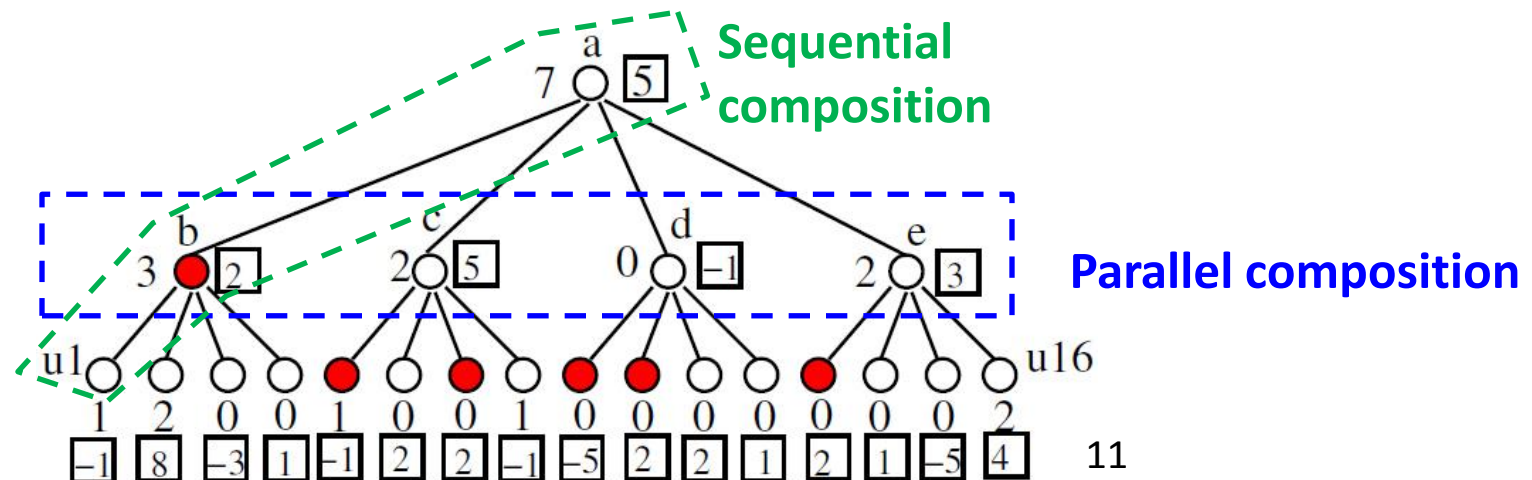
- ◆ **Build**: adapt existing methods to have differential privacy
- ◆ **Release**: a private description of data distribution (in the form of bounding boxes and noisy counts)

Building a Private kd-tree

- ◆ Process to build a private kd-tree
 - **Input:** maximum height h , minimum leaf size L , data set
 - Choose dimension to split
 - Get (private) median in this dimension
 - Create child nodes and add noise to the counts
 - Recurse until:
 - Max height is reached
 - Noisy count of this node less than L
 - Budget along the root-leaf path has used up
- ◆ The entire PSD satisfies DP by the composition property

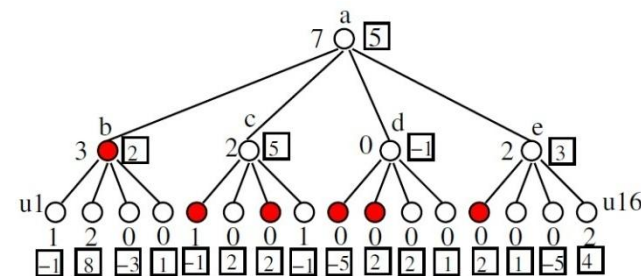
Building PSDs – privacy budget allocation

- ◆ Data owner specifies a total budget reflecting the level of anonymization desired
- ◆ Budget is split between medians and counts
 - Tradeoff accuracy of division with accuracy of counts
- ◆ Budget is split across levels of the tree
 - Privacy budget used along any root-leaf path should total ϵ



Privacy budget allocation

- ◆ How to set an ϵ_i for each level?
 - Compute the number of nodes touched by a ‘typical’ query
 - Minimize variance of such queries
 - **Optimization**: $\min \sum_i 2^{h-i} / \epsilon_i^2$ s.t. $\sum_i \epsilon_i = \epsilon$
 - Solved by $\epsilon_i \propto (2^{(h-i)})^{1/3} \epsilon$: more to leaves
 - Total error (variance) goes as $2^h / \epsilon^2$



- ◆ Tradeoff between noise error and spatial uncertainty
 - Reducing h drops the noise error
 - But lower h increases the size of leaves, more uncertainty

Post-processing of noisy counts

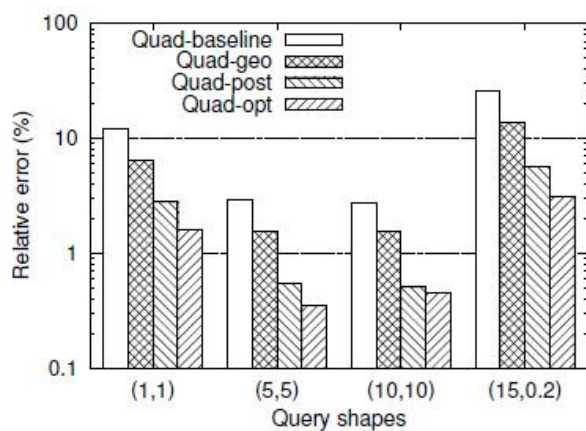
- ◆ Can do additional post-processing of the noisy counts
 - To improve query accuracy and achieve consistency
- ◆ **Intuition**: we have count estimate for a node and for its children
 - Combine these independent estimates to get better accuracy
 - Make consistent with some true set of leaf counts
- ◆ Formulate as a linear system in n unknowns
 - Avoid explicitly solving the system
 - Expresses optimal estimate for node v in terms of estimates of ancestors and noisy counts in subtree of v
 - Use the tree-structure to solve in three passes over the tree
 - Linear time to find optimal, consistent estimates

Experimental study

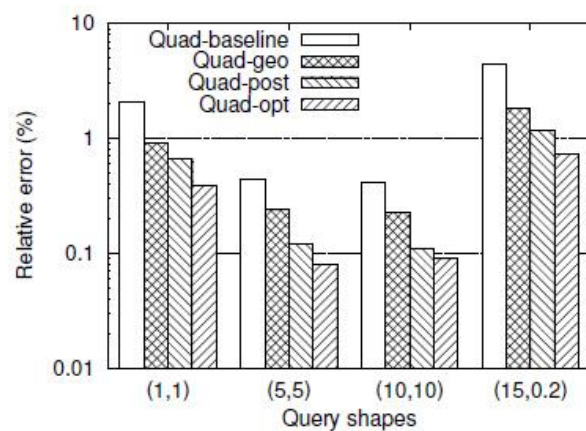
- ◆ 1.63 million coordinates from US TIGER/Line dataset
 - Road intersections of US States
- ◆ Queries of different shapes, e.g. square, skinny
- ◆ Measured median relative error of 600 queries for each shape

Experimental study

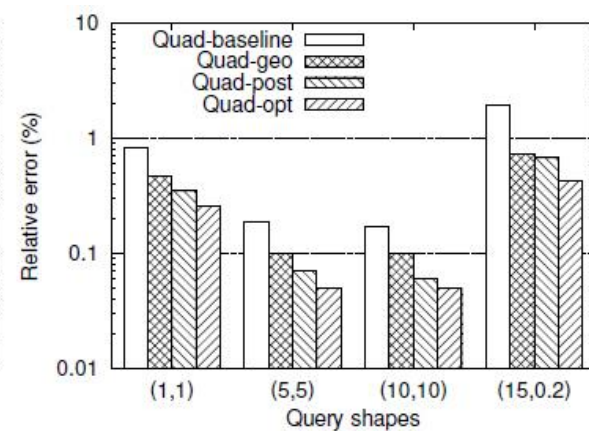
◆ Effectiveness of geometric budget and post-processing



(a) $\epsilon = 0.1$



(b) $\epsilon = 0.5$

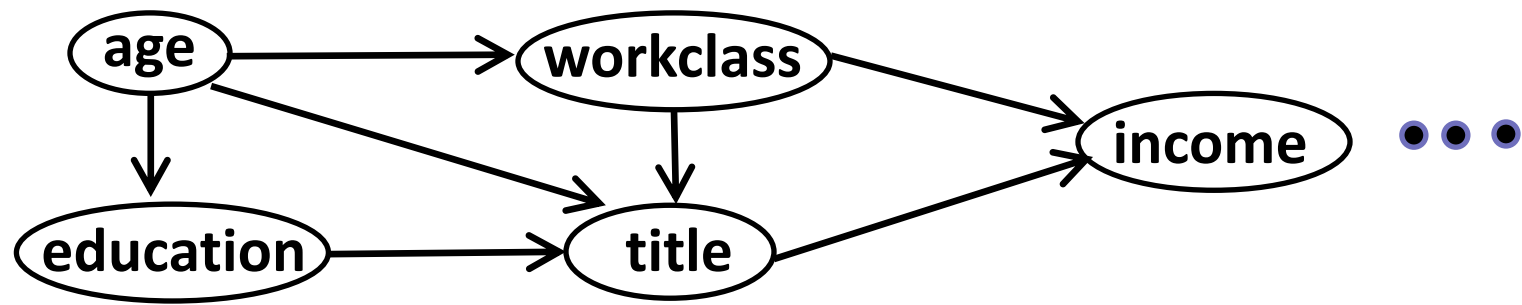


(c) $\epsilon = 1.0$

- Relative error reduced by up to an order of magnitude
- Most effective when limited privacy budget

PrivBayes [SIGMOD14]

- ◆ Directly materializing a full distribution: low signal, high noise
- ◆ Use a **Bayesian network** to approximate the full-dimensional distribution by lower-dimensional ones:



$$\begin{aligned} \Pr[H] \approx & \Pr[\text{age}] \cdot \Pr[\text{education}|\text{age}] \cdot \Pr[\text{workclass}|\text{age}] \cdot \\ & \Pr[\text{title}|\text{age}, \text{education}, \text{workclass}] \cdot \Pr[\text{income}|\text{workclass}, \text{title}] \cdot \\ & \Pr[\text{marital status}|\text{age}, \text{income}] \dots \end{aligned}$$

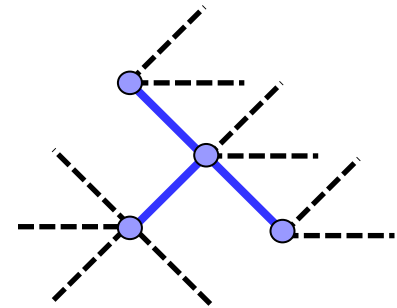
low-dimensional distributions: **high signal-to-noise**

PrivBayes (SIGMOD14)

- ◆ **STEP 1:** Choose a suitable Bayesian Network BN
 - in a differentially private way
- ◆ **STEP 2:** Compute distributions implied by edges of BN
 - straightforward to do under differential privacy (Laplace)
- ◆ **STEP 3:** Generate synthetic data by sampling from the BN
 - post-processing: no privacy issues
- ◆ Evaluate utility of synthetic data for variety of different tasks

STEP 1: 1-degree BN [Chow-Liu'68]

- ◆ Optimal 1-degree BN maximizes $\sum_{(A_i, A_j): \text{edge}} MI(A_i, A_j)$
(MI: mutual information)
- ◆ Follows Prim's MST algorithm:
 - Pick arbitrary starting point $S = \{A_1\}$
 - For $i = 1 \dots d-1$:
 - Pick $e_i = (A_i, A_{i+1})$ to maximize $MI(e_i)$ where $A_i \in S$ and $A_{i+1} \notin S$
 - Add e_i to BN, $S \leftarrow S \cup \{A_{i+1}\}$
- ◆ Use **exponential mechanism** to pick edge with high mutual information at each step
- ◆ For higher-degree BNs, pick a k 'th order distribution at each step
 - Pick a set of parents A_i for A_{i+1} with high mutual information
- ◆ Problem solved?



Choosing an edge in BN

First attempt: define $\text{score}(\text{edge}) = \text{MI}(\text{edge})$

- ◆ We prove $\Delta(\text{MI}) = \Theta(\log n / n)$, where $n = |D|$, size of the data
- ◆ Applying exponential mechanism, the MST algorithm chooses $e_i = (A_i \in S, A_{i+1} \notin S)$ with probability

$$\Pr[e_i] \propto \exp\left(\frac{\varepsilon n}{2} \frac{\text{MI}(e_i)}{\log n}\right)$$

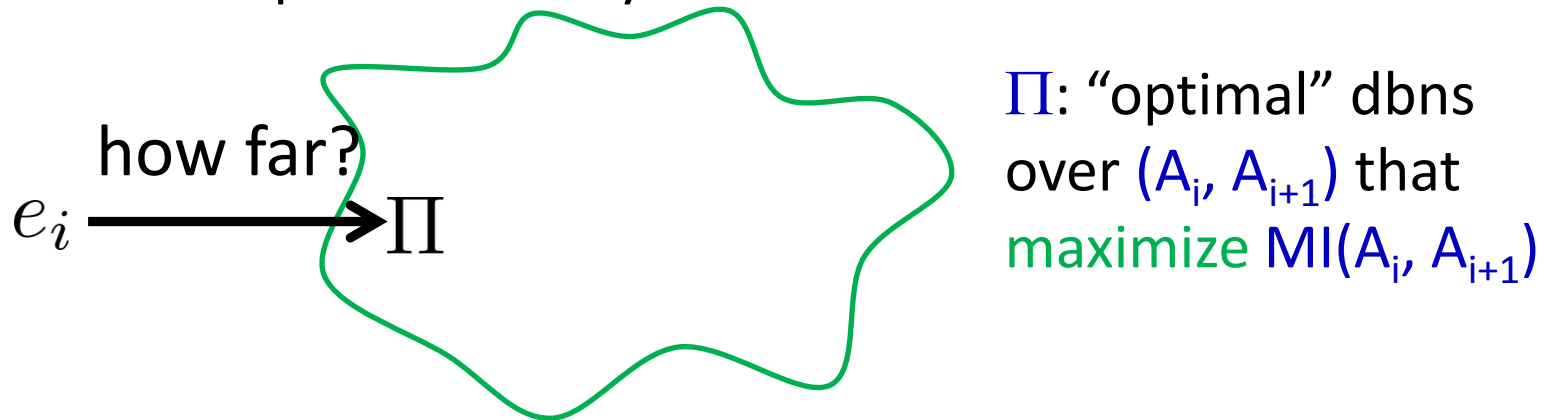
- ◆ **Problem:** sensitivity $\Delta(\text{MI})$ can be large compared to MI
 - Gives high chance of sampling an edge with low information
 - Can we find a better quality function for exponential mechanism?

Defining a new score function

GOAL: $Pr[e_i] \propto \exp\left(\frac{\varepsilon n}{2} \text{score}(e_i)\right)$

and large scores should correspond to large MI's

IDEA: define **score** to agree with MI at maximum values
and interpolate linearly in-between



We define: $\text{score}(e_i) = -\frac{1}{2} \min_{\Pi: \text{optimal}} \|e_i - \Pi\|_1$

$\Delta(\text{score}) = 1/n$ by triangle inequality

Optimal Distributions

	A_i				
A_{i+1}					
					
					

Can prove that necessary conditions for optimality are:

1. **Uniform marginal:**

$$\sum (\text{green oval}) = \frac{1}{|A_{i+1}|} \text{ in each row}$$

2. **Sparse:** At most one  per column

Infinitely many such distributions!

Optimal Distributions

A_i

					
A_{i+1}					
					

However, can show that

- ◆ size of the  does not matter;
- ◆ only their *position* matters

But still (doubly) exponentially many possibilities...

Define $\text{score}(e_i)$ by discrete optimization over layouts

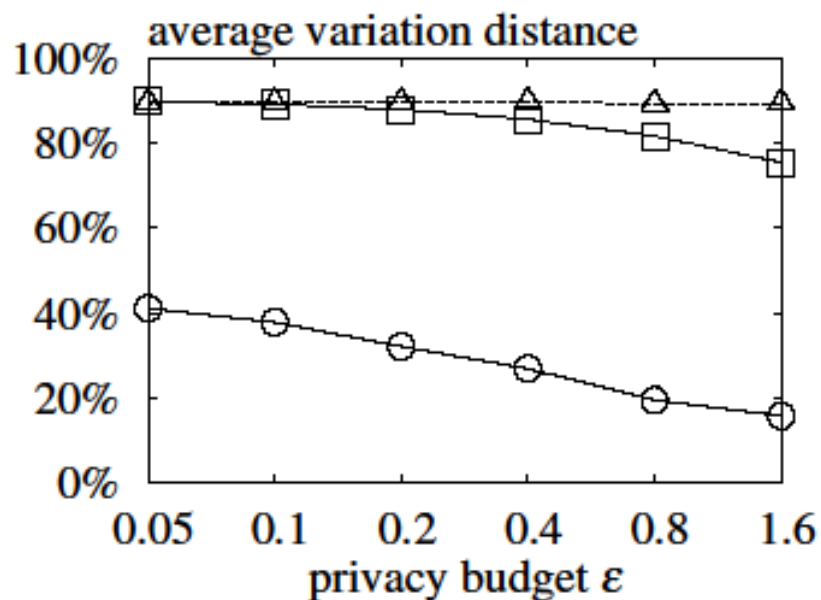
- ◆ **General case**: solved by Integer Program
- ◆ When $|A_{i+1}| = 2$: can solve by Dynamic Program

Naïve Bayes Summary

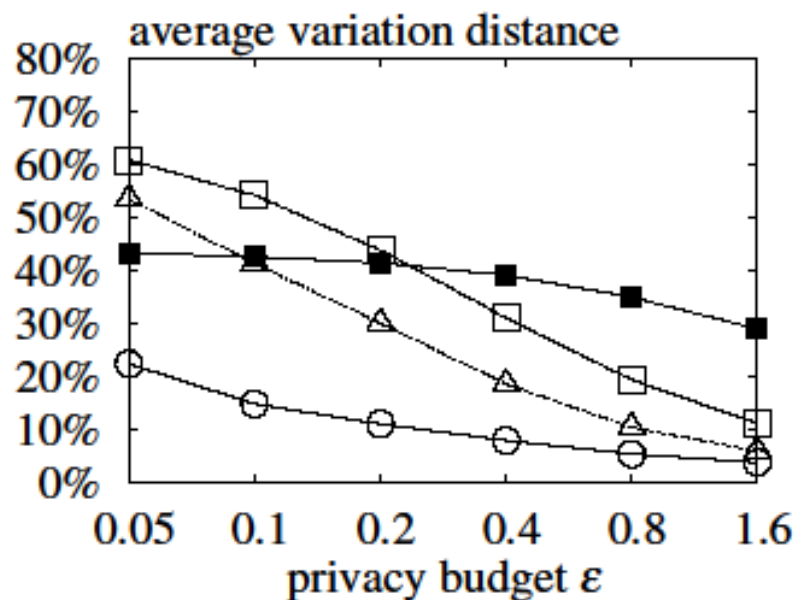
- ◆ To choose next distribution to materialize:
 - For each possible next child A_{i+1}
 - Find optimal distribution via discrete optimization (DP or IP)
 - Find **score** as L1 distance of $\text{Pr}[A_{i+1}, A_i]$ from optimal
 - Use exponential mechanism to pick next based on score
- ◆ Can pick the degree of the Bayesian network based on estimated noise (independent of data)
- ◆ Generate data from the released (private) Bayesian network
 - Plug into any desired application, e.g. classification, regression

Experiments: Counting Queries

—○— *PrivBayes* —□— *Laplace* —△— *Fourier* —■— *Histogram*



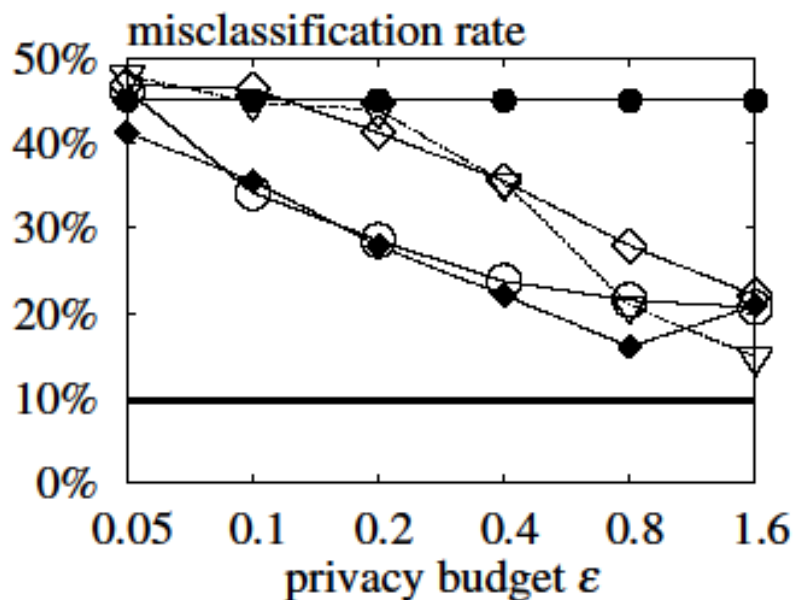
Adult dataset



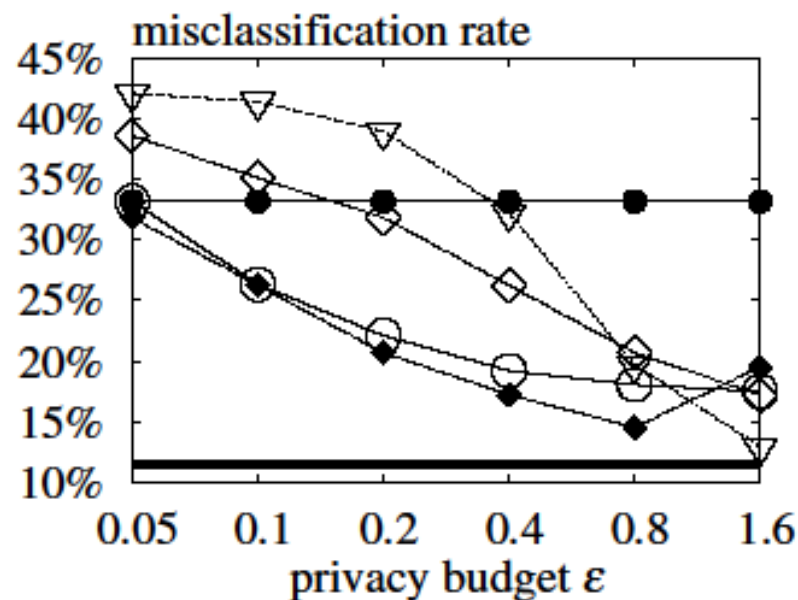
NLTCs dataset

Query load = Compute all 3-way marginals

Experiments: Classification



Y = education: post-secondary degree?



Y = marital status: never married?

Adult dataset, build 4 classifiers

Concluding Remarks

- ◆ Differential privacy can be applied effectively for data release
- ◆ **Solutions**: classical techniques (e.g., sampling, kd-tree, BN) adapted to provide differentially privacy
 - With a different trade off: minimize the **privacy cost**
- ◆ Many open problems remain:
 - **Transition** these techniques to tools for data release
 - Extend to other forms of data: mobility data, graph data
 - Allow **joining** anonymized data sets accurately
 - Obtain alternate (workable) **privacy definitions**

Thank you!